

# 1 Case 33

The minimal zero supports are given by (1,2,3),(1,2,4),(1,3,5),(2,4,5),(3,5,6),(4,5,6).

$$A = \begin{pmatrix} 1 & -\cos(\phi_2) & -\cos(\phi_1) & \cos(\phi_2 + \phi_3) & \cos(\phi_1 + \phi_4) & b_1 \\ -\cos(\phi_2) & 1 & \cos(\phi_1 + \phi_2) & -\cos(\phi_3) & \cos(\phi_3 + \phi_5) & b_2 \\ -\cos(\phi_1) & \cos(\phi_1 + \phi_2) & 1 & b_3 & -\cos(\phi_4) & \cos(\phi_4 + \phi_6) \\ \cos(\phi_2 + \phi_3) & -\cos(\phi_3) & b_3 & 1 & -\cos(\phi_5) & \cos(\phi_5 + \phi_6) \\ \cos(\phi_1 + \phi_4) & \cos(\phi_3 + \phi_5) & -\cos(\phi_4) & -\cos(\phi_5) & 1 & -\cos(\phi_6) \\ b_1 & b_2 & \cos(\phi_4 + \phi_6) & \cos(\phi_5 + \phi_6) & -\cos(\phi_6) & 1 \end{pmatrix}$$

The zeros are given by the columns:

$$(u_1, u_2, u_3, u_4, u_5, u_6) = \begin{pmatrix} \sin(\phi_1 + \phi_2) \\ \sin(\phi_1) \\ \sin(\phi_2) \\ 0 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} \sin(\phi_3) \\ \sin(\phi_2 + \phi_3) \\ 0 \\ \sin(\phi_2) \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} \sin(\phi_4) \\ 0 \\ \sin(\phi_1 + \phi_4) \\ 0 \\ \sin(\phi_1) \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ \sin(\phi_5) \\ 0 \\ \sin(\phi_3 + \phi_5) \\ \sin(\phi_3) \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ \sin(\phi_6) \\ 0 \\ \sin(\phi_4 + \phi_6) \\ \sin(\phi_4) \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ \sin(\phi_6) \\ \sin(\phi_5 + \phi_6) \\ \sin(\phi_5) \end{pmatrix}$$

The zeros in this case are dependent.  $a * u_1 + b * u_2 + c * u_3 + d * u_4 + e * u_5 + f * u_6 = 0$

$$a = \frac{\sin(\phi_1 - \phi_3 + \phi_4 - \phi_5) \sin(\phi_1 - \phi_2 - \phi_3 + \phi_4 - \phi_5)}{\sin(\phi_1)}$$

$$b = \frac{\sin(\phi_1 - \phi_3 + \phi_4 - \phi_5) (\sin(\phi_2) - \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5))}{\sin(\phi_3)}$$

$$c = \frac{\sin(\phi_3 - \phi_4 + \phi_5)}{\sin(\phi_4)} \left( \frac{\sin(\phi_2) (\sin(\phi_2) - \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5))}{\sin(\phi_3 - \phi_4 + \phi_5)} + \frac{\sin(\phi_1 - \phi_2 - \phi_3 + \phi_4 - \phi_5) \sin(\phi_2)}{\sin(\phi_1)} \right)$$

$$d = -\frac{\sin(\phi_5 - \phi_4)}{\sin(\phi_5)} \left( \frac{\sin(\phi_1) \sin(\phi_2) ((\sin(\phi_2) - \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5))}{\sin(\phi_5 - \phi_4)} + \frac{\sin(\phi_1 - \phi_2 - \phi_3 + \phi_4 - \phi_5)}{\sin(\phi_1)} \right) + \frac{\sin(\phi_2) (\sin(\phi_2) - \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5)) \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5)}{\sin(\phi_3 - \phi_4 + \phi_5) \sin(\phi_3)}$$

$$T = \frac{\sin(\phi_3)}{\sin(\phi_5)} \left( \frac{\sin(\phi_1) \sin(\phi_2) ((\sin(\phi_2) - \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5))}{\sin(\phi_5 - \phi_4)} + \frac{\sin(\phi_1 - \phi_2 - \phi_3 + \phi_4 - \phi_5)}{\sin(\phi_1)} \right) + \frac{\sin(\phi_2) (\sin(\phi_2) - \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5)) \sin(\phi_1 - \phi_3 + \phi_4 - \phi_5)}{\sin(\phi_3 - \phi_4 + \phi_5) \sin(\phi_3)}$$

$$e = \frac{\sin(\phi_5)}{\sin(\phi_6)} T$$

$$f = -\frac{\sin(\phi_4)}{\sin(\phi_6)} T$$