

# Symmetric Indefinite Triangular Factorization Revealing the Rank Profile Matrix

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# Context

## Applications of symmetric Gaussian elimination

- Symmetric linear system solving
- Signature
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## Compared to unsymmetric Gaussian elimination

- Save a factor of 2 in time complexity
- Invariants specific to symmetric matrices (signature)

## Motivation here

- `fsytrf`: finite field dense symmetric elimination in `fflas-ffpack`
- to be lifted for `LinBox` signature over  $\mathbb{Z}$
- reduction to matrix product:  $O(n^2 r^{\omega-2})$  and BLAS3
- investigate symmetric rank profile matrix and related pivoting

# Outline

- 1 State of the art on symmetric factorizations
- 2 Rank profile and pivoting
- 3 Algorithms
- 4 The characteristic 2 case
- 5 Performance

# Symmetric factorizations

## Symmetric Decomposition

$$\begin{array}{|c|} \hline \mathbf{A} \\ \hline \end{array} = \begin{array}{|c|} \hline \mathbf{B} \\ \hline \end{array} \begin{array}{|c|} \hline \mathbf{B}^T \\ \hline \end{array}$$

## Exists for

Field with sqrt &  
Generic rank profile

# Symmetric factorizations

## Symmetric Decomposition

$$A = B \begin{matrix} \diagdown \\ \diagup \end{matrix} B^T$$

$$A = L \begin{matrix} \diagdown \\ \diagup \end{matrix} D \begin{matrix} \diagdown \\ \diagup \end{matrix} L^T$$

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## Symmetric Decomposition

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Generic rank profile

$$A = \begin{bmatrix} P \\ & L \\ & & D \\ & & & L^T \\ & & & & P^T \end{bmatrix}$$

No  $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ -like blocks

$$A = \begin{bmatrix} P \\ & L \\ & & T \\ & & & L^T \\ & & & & P^T \end{bmatrix}$$

Any [Parlett-Reid 1970]  
 $T$  tridiagonal

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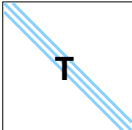
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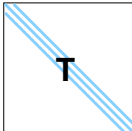
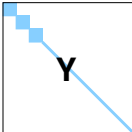
⋮

Any [Bunch-Kaufmann 1977]  
 $Y$  with  $1 \times 1$  and  $2 \times 2$  blocks

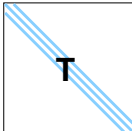
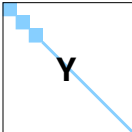
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Form	Properties		
	<p>[Parlett-Reid 1970]            Diagonal Pivoting            Iterative  <math>\frac{2}{3}n^3</math></p>	<p>[Bunch-Parlett 1971]            Full pivoting            Iterative  <math>\frac{2}{3}n^3</math></p>	<p>[Aasen 1971]            Partial pivoting            Iterative  <math>\frac{1}{3}n^3</math></p>

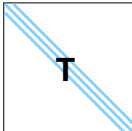

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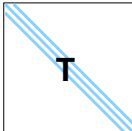
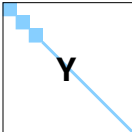
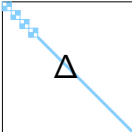
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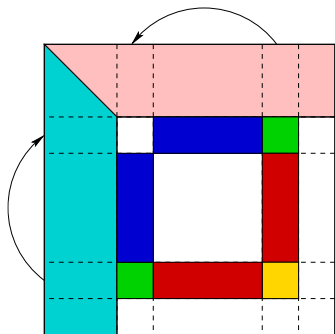
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	<p>Here</p> <p>Pivoting revealing the rank profile matrix</p> <p>Recursive for any matrix</p> <p><math>O(n^2 r^{\omega-2})</math> (gives <math>\frac{1}{3}n^3</math> when <math>rank=n</math> &amp; <math>\omega=3</math>)</p>		

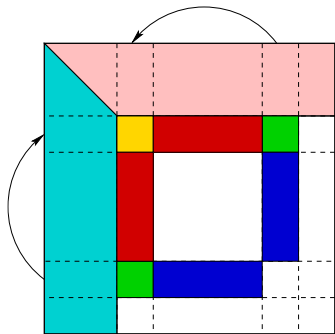
# Symmetric pivoting



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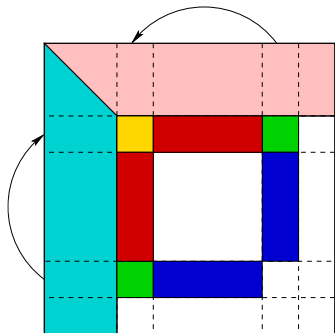


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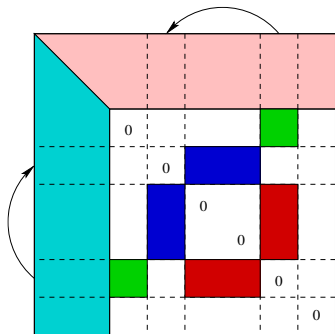
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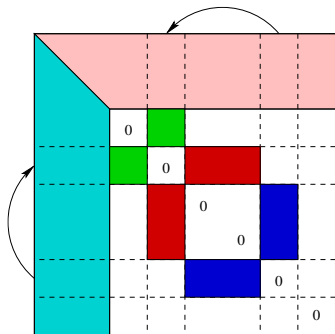
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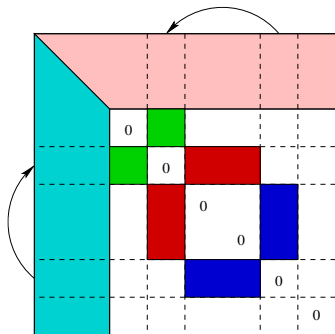
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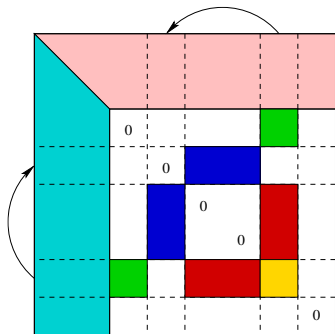
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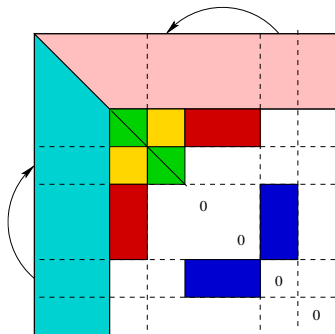
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- Off-diagonal pivoting with zero diagonal  
 $\Rightarrow L\Delta L^T$  with  $\Delta$  block diagonal,  $1 \times 1$   
 or  $2 \times 2 \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  blocks

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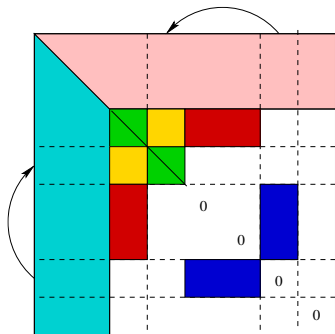
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 $\Rightarrow LDL^T$  with  $D$  diagonal  
 $\Rightarrow$  requires division by 2



# The rank profile matrix

## Rank Profiles

Given a matrix  $A$  of rank  $r$ :

## Example

$$A = \begin{pmatrix} 0 & 0 & 0 & 2 \\ 3 & 0 & 4 & 0 \\ 0 & 0 & 0 & 0 \\ 5 & 0 & 0 & 0 \end{pmatrix}$$

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Given a matrix  $A$  of rank  $r$ :

- RRP (Row Rank Profile): first  $r$  linearly independent rows

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Given a matrix  $A$  of rank  $r$ :

- RRP (Row Rank Profile): first  $r$  linearly independent rows
- CRP (Column Rank Profile): first  $r$  linearly independent columns

## Example

$$A = \begin{pmatrix} \begin{pmatrix} 0 \\ 3 \\ 0 \\ 5 \end{pmatrix} & \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} & \begin{pmatrix} 0 \\ 4 \\ 0 \\ 0 \end{pmatrix} & \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix} \end{pmatrix}$$

# The rank profile matrix

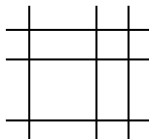
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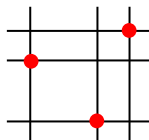
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## RPM (Rank Profile Matrix)

The unique  $\mathcal{R}_A$  such that any pair of  $(i, j)$ -leading sub-matrix of  $\mathcal{R}_A$  and of  $A$  have the same rank.

# Pivoting revealing the rank profile matrix (unsymmetric)

[D., P., Sultan. ISSAC'15.] *Computing the Rank Profile Matrix.*

## Definition

$A = PLUQ$  reveals the rank profile matrix if  $P \begin{bmatrix} I_r & \\ & 0 \end{bmatrix} Q = \mathcal{R}_A$

Search	Row perm.	Col. perm.	RowRP	ColRP	$\mathcal{R}_A$	Instance
Row order	Transposition	Transposition	★			[IMH82] [JPS13]
Col. order	Transposition	Transposition		★		[KG85] [JPS13]
Lexico.	Transposition	Transposition	★			[Sto00]
Lexico.	Transposition	Rotation	★	★	★	[DPS15]
Lexico.	Rotation	Rotation	★	★	★	[DPS15]
Rev. lex.	Transposition	Transposition		★		[Sto00]
Rev. lex.	Rotation	Transposition	★	★	★	[DPS15]
Rev. lex.	Rotation	Rotation	★	★	★	[DPS15]
Product	Rotation	Transposition	★			[DPS15]
Product	Transposition	Rotation		★		[DPS15]
Product	Rotation	Rotation	★	★	★	[DPS13]

# Pivoting revealing the rank profile matrix (symmetric case)

## Definition

$A = PL\Delta L^T P^T$  reveals the rank profile matrix  $\mathcal{R}_A$  if

$$P\Delta P^T = \text{Diag}(d_1, \dots, d_n)\mathcal{R}_A$$

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- 1 Find pivot with minimal coordinates w.r.t.
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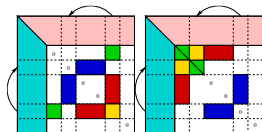
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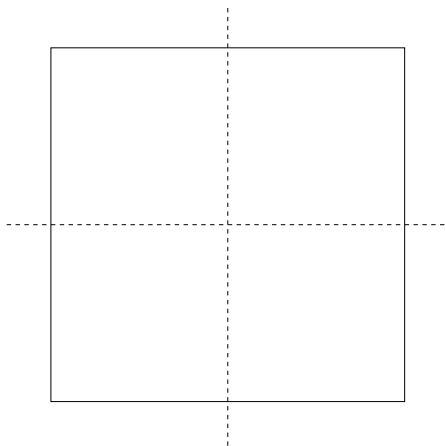
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- ⇒ Off-diagonal pivoting with non-zero diagonal
- ⇒ Requires division by 2.

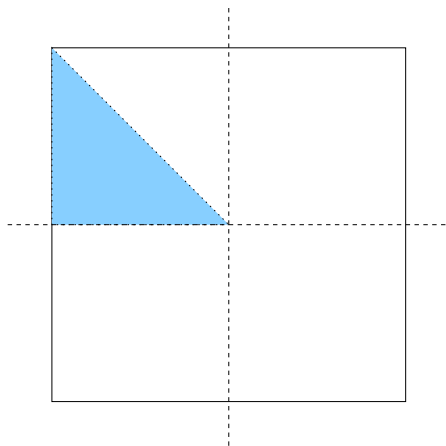


# The recursive algorithm: full rank case



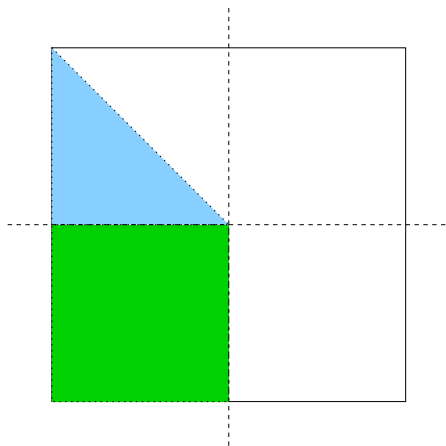
④ Split

# The recursive algorithm: full rank case



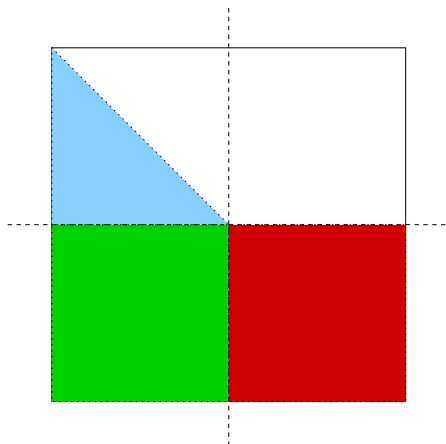
- 1 Split
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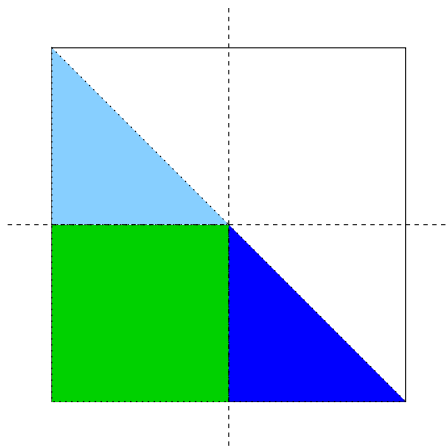
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- 4 SYRK:  $H \leftarrow A_{22} - G G^T$

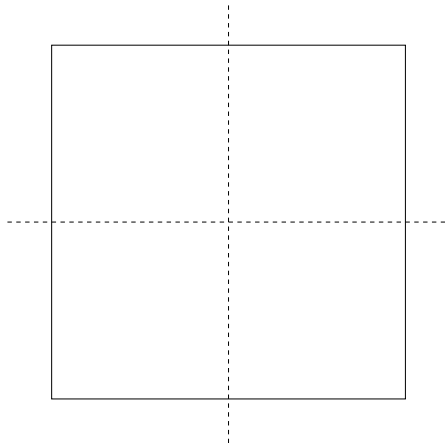
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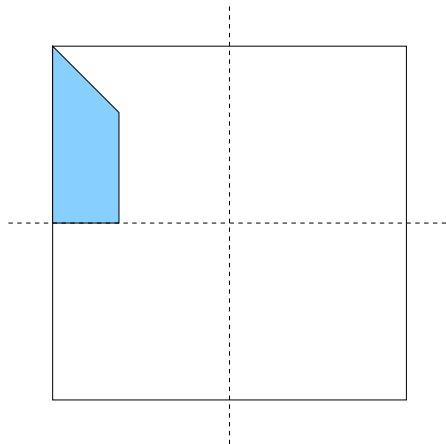
# The recursive algorithm: arbitrary rank case

1 Split



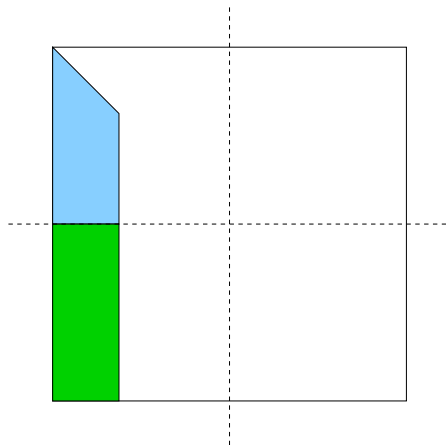
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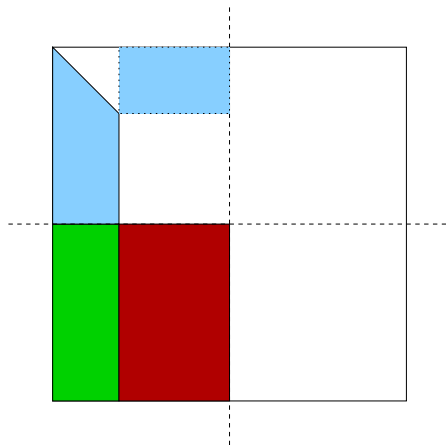


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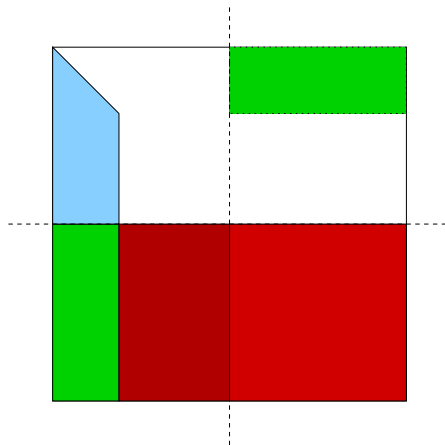
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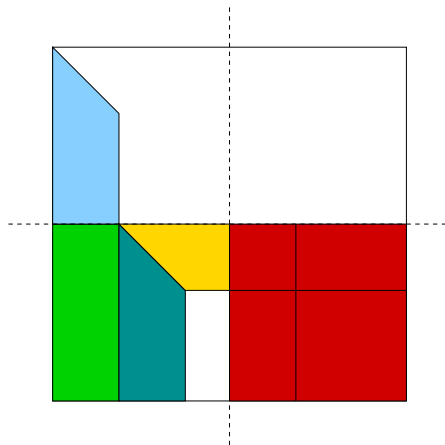
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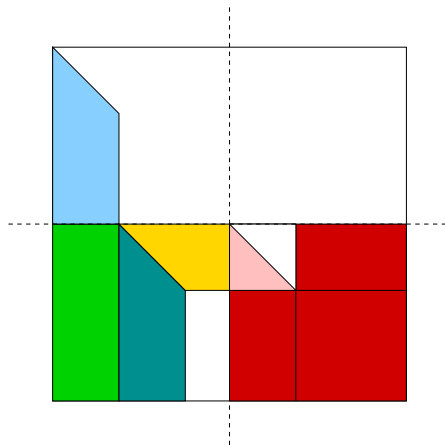
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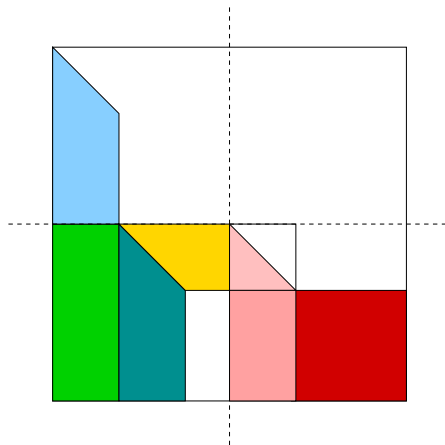
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- 6 PLUQ:  $K = P_2 L_2 U_2 Q_2$

# The recursive algorithm: arbitrary rank case



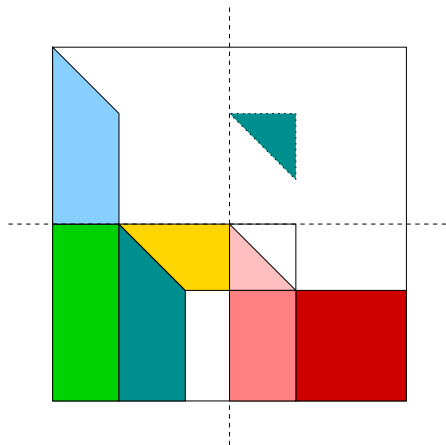
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- 6 PLUQ:  $K = P_2 L_2 U_2 Q_2$
- 7 TRSYR2K: find  $X$  s.t.  
 $L_2 X^T + X L_2^T = H_{11}$

# The recursive algorithm: arbitrary rank case



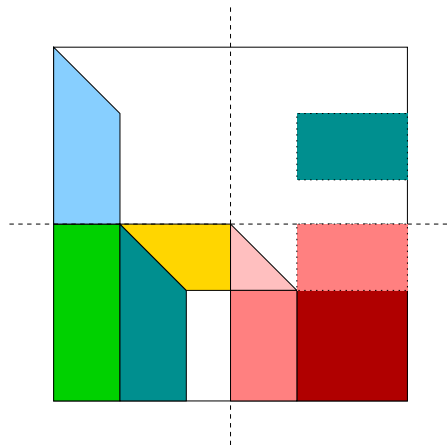
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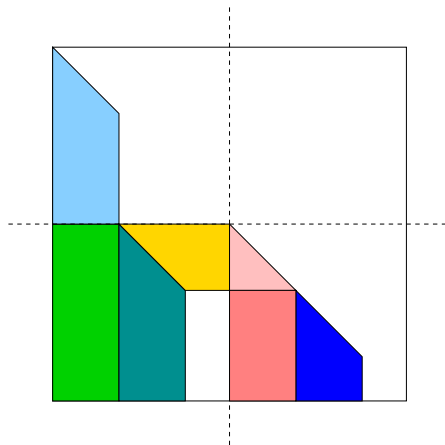
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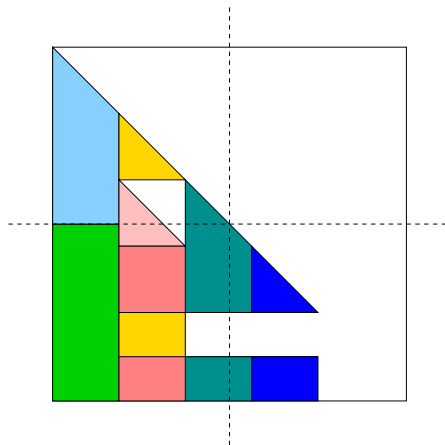


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- 12 Permutation

# The trsyl2k routine

## Problem

Given  $C$  symmetric and  $L$  lower triangular

Find  $X$  lower triangular such that

$$LX^T + XL^T = C$$

$$\begin{bmatrix} L_1 & \\ L_2 & L_3 \end{bmatrix} \begin{bmatrix} X_1^T & X_2^T \\ & X_3^T \end{bmatrix} + \begin{bmatrix} X_1 & \\ X_2 & X_3 \end{bmatrix} \begin{bmatrix} L_1^T & \\ & L_2^T \\ & & L_3^T \end{bmatrix} = \begin{bmatrix} C_1 & & \\ & C_2 & \\ & & C_3 \end{bmatrix}.$$

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$$L_1 X_1^T + X_1 L_1^T = C_1$$

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recurse

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$$L_2X_1^T + X_2L_1^T = C_2$$

① Find  $X_1$  s.t.  $L_1X_1^T + X_1L_1^T = C_1$

recurse

②  $Y \leftarrow C_2 - L_2X_1^T$

trmm

③  $X_2 \leftarrow (L_1^T)^{-1}Y$

trsm

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sy2k

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- |   |   |         |
|---|---|---------|
| 1 | Find $X_1$ s.t. $L_1X_1^T + X_1L_1^T = C_1$ | recurse |
| 2 | $Y \leftarrow C_2 - L_2X_1^T$               | trmm    |
| 3 | $X_2 \leftarrow (L_1^T)^{-1}Y$              | trsm    |
| 4 | $Z \leftarrow C_3 - L_2X_2^T + X_2L_2^T$    | syr2k   |
| 5 | Find $X_3$ s.t. $L_3X_3^T + X_3L_3^T = Z$   | recurse |

## Problem in characteristic 2

Consider  $\begin{bmatrix} 0 & c \\ c & d \end{bmatrix}$  (with  $\mathcal{R} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ )

Diagonal pivoting:  $\begin{bmatrix} 0 & c \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{c}{d} & 1 \end{bmatrix} \begin{bmatrix} d & \\ & -\frac{c^2}{d} \end{bmatrix} \begin{bmatrix} 1 & \frac{c}{d} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$



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Off-diagonal pivoting:  $\begin{bmatrix} 0 & c \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & \\ & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{d}{2c} & 1 \end{bmatrix} \begin{bmatrix} 0 & c \\ c & 0 \end{bmatrix} \begin{bmatrix} 1 & \frac{d}{2c} \\ 0 & 1 \end{bmatrix}$

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Diagonal pivoting breaks RPM-revealing property

- $\Rightarrow$  off-diagonal pivoting required
- $\Rightarrow$  division by 2 required

In characteristic 2

$\Rightarrow$  In general there is **no** RPM-revealing  $P \cdot L \cdot \Delta \cdot L^T \cdot P^T!$

## Characteristic 2: Preserve $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ factors

- Compute instead  $A = P \cdot L \cdot D \cdot \Psi \cdot L^T \cdot P^T$ :

$\Rightarrow D$  diagonal,  $\Psi$  block diagonal with  $1 \times 1$ ,  $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$  blocks

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- From this **intermediate form**:
  - Either recover  $\mathcal{R}_A = P \cdot \mathcal{R}_\Psi \cdot P^T$ ;
  - Or use:

$$\begin{bmatrix} c & c \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ c/d & 1 \end{bmatrix} \cdot \begin{bmatrix} d & \\ & -c^2/d \end{bmatrix} \cdot \begin{bmatrix} 1 & c/d \\ & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix}$$

☺ + commuting

$\Rightarrow \tilde{P} \cdot \tilde{L} \cdot \Delta \cdot \tilde{L}^T \cdot \tilde{P}^T$  symmetric factorization (but  $\mathcal{R}_A$  is lost)

# Iterative base case

Practical performance:

⚠ Stop recursion (less mod reductions/data move on small matrices)

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- ⚠ Stop recursion (less mod reductions/data move on small matrices)
- ⇒ iterative base case and cascading
  - pivot search minimizing the lexicographic order
  - cyclic shifts on the row and columns
  - Crout elimination schedule

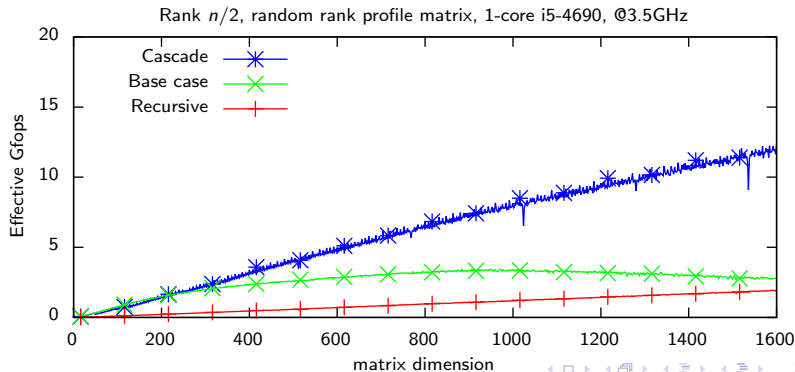
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## LAPACK vs FFPACK modulo 8 388 593

$n$	LAPACK		FFPACK	
	dgetrf (LU)	dsytrf (LDLT)	fgetrf (LU)	fsytrf (LDLT)
5000	2.01s	1.60s	3.90s	1.59s
10000	14.95s	11.98s	24.12s	10.90s

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