

Symmetric Determinantal Representations of Polynomials

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Rennes – Séminaire de Calcul Formel – November 26, 2010

The problem

$$(x + 3y)z = \det \begin{pmatrix} 0 & x & 3 & 0 & 0 \\ 0 & 1 & 0 & 0 & z \\ 0 & 0 & 1 & y & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{pmatrix}$$

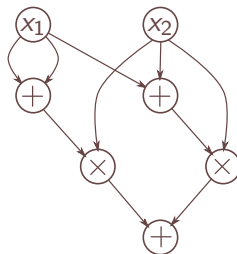
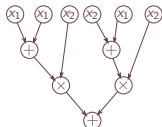
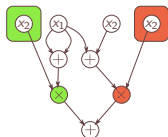
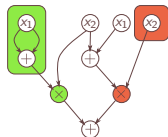
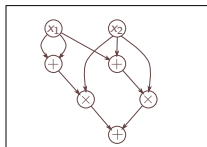
- Formal polynomial

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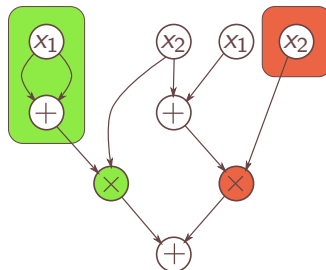
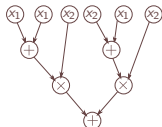
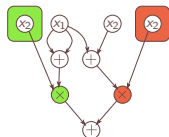
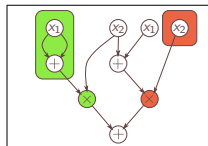
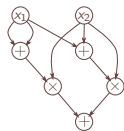
- Formal polynomial
- Smallest possible dimension of the matrix

Representations of polynomials



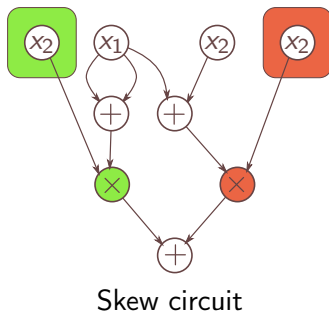
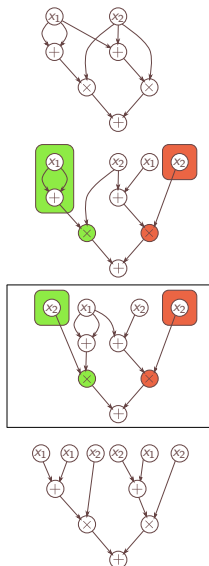
Circuit

Representations of polynomials

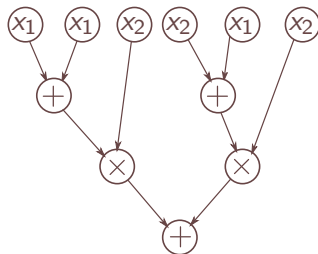
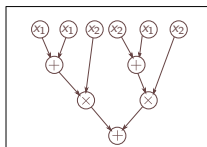
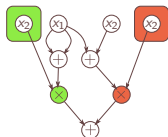
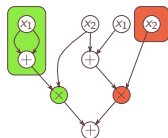
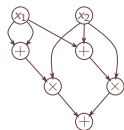


Weakly-skew circuit

Representations of polynomials



Representations of polynomials



Formula

Motivation

L. G. Valiant, Completeness classes in algebra, STOC 79

↪ Universality of the determinant

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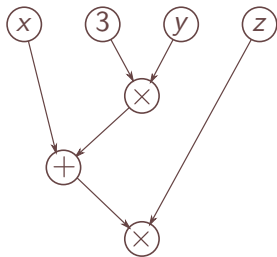
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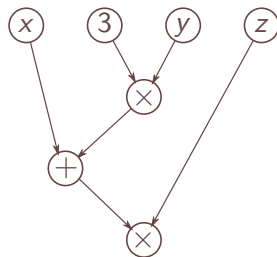
“We conclude that for the problem of finding a subexponential formula for a polynomial when one exists, linear algebra is essentially the only technique in the sense that it is always applicable.”

An example

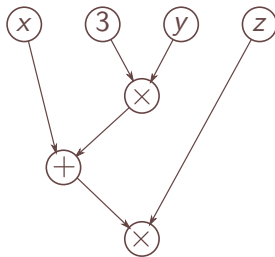
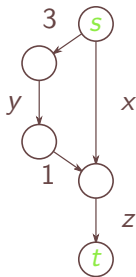
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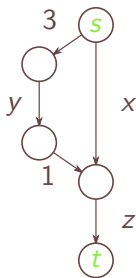


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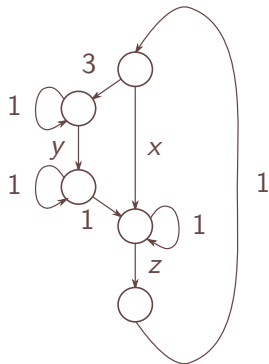
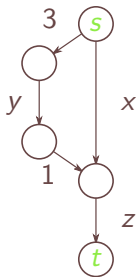


Arithmetic Branching Program

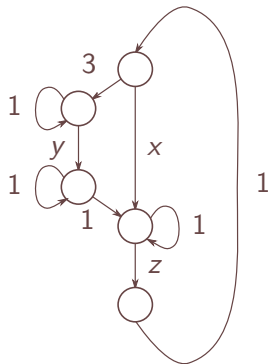
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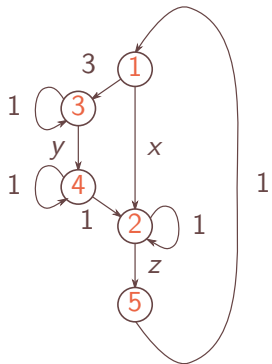


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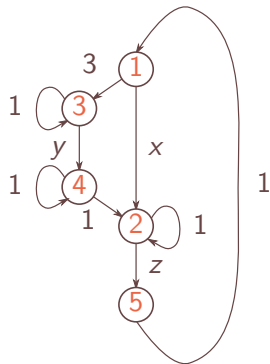
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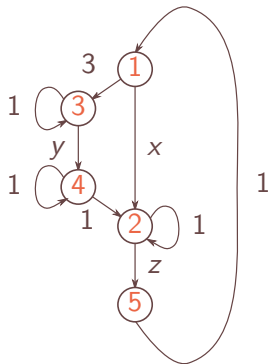
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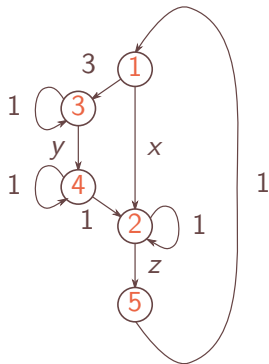


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- Up to signs, $\det A =$ sum of the weights of cycle covers in G

Outline

- 1 From polynomials to determinants
- 2 From polynomials to determinants of symmetric matrices
- 3 Characteristic 2
- 4 Comparison with Convex Geometry Literature

Upper bounds

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- $e + 1$ if there is **at least one addition** in the formula: H. Liu and K.W. Regan, in *Improved construction for universality of determinant and permanent* (Inf. Process. Lett., 2006)

Valiant's construction (1/3)

- Input: a formula representing a polynomial $\varphi \in \mathbb{K}[X_1, \dots, X_n]$ of size e

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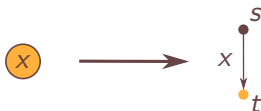
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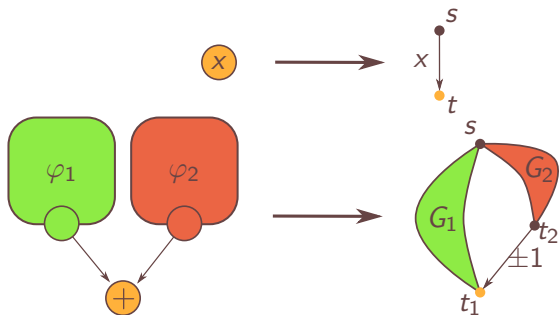
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- In between: a graph G of size $(e + 1)$ whose adjacency matrix is A

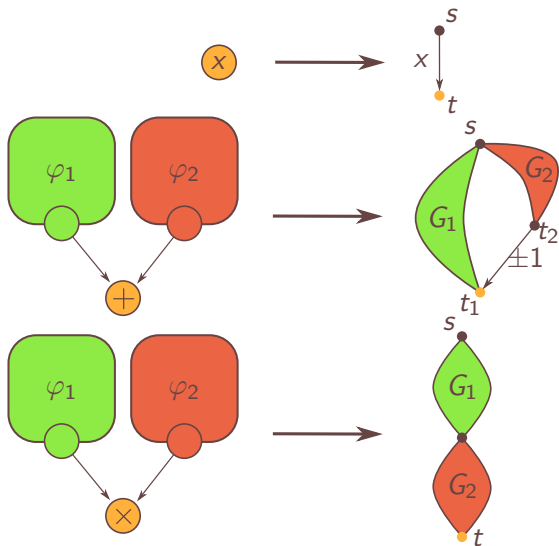
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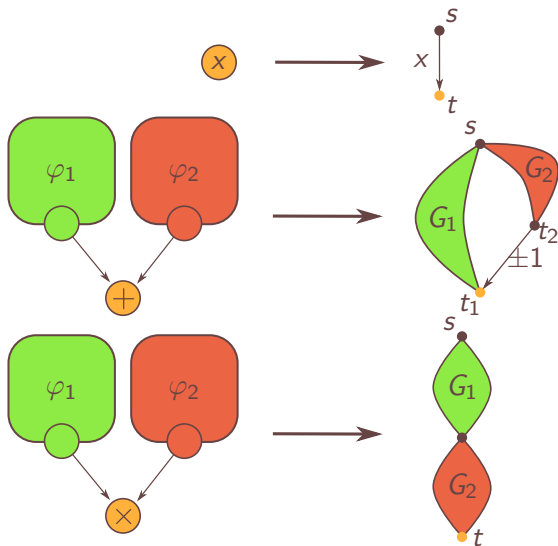
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Invariant

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Theorem

For a size- e formula, this construction yields a size- $(e + 1)$ graph. Let A be the adjacency matrix of G' . Then $\det(A) = \varphi$.

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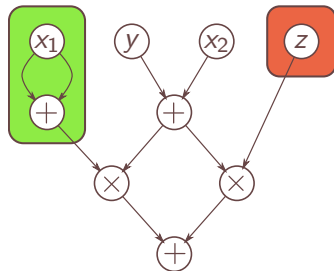
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Toda-Malod's construction (1/3)

- Input: a **weakly-skew** circuit of size e with i variable inputs representing φ

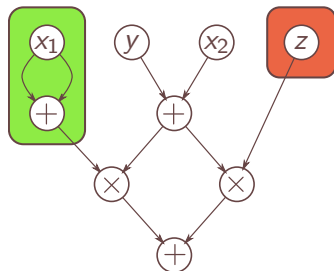
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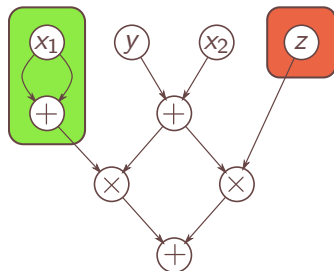
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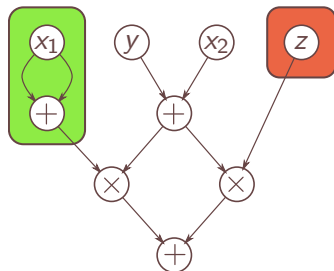
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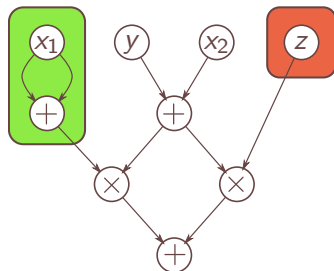
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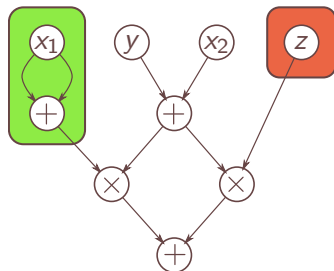
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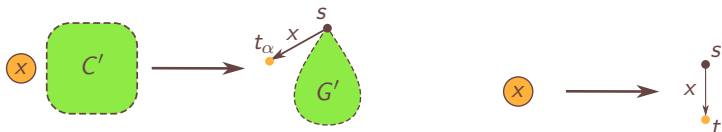
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- **Reusable** gate: not in a **closed** subcircuit

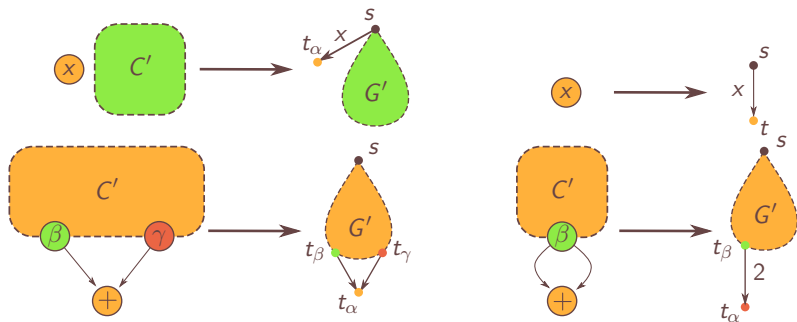


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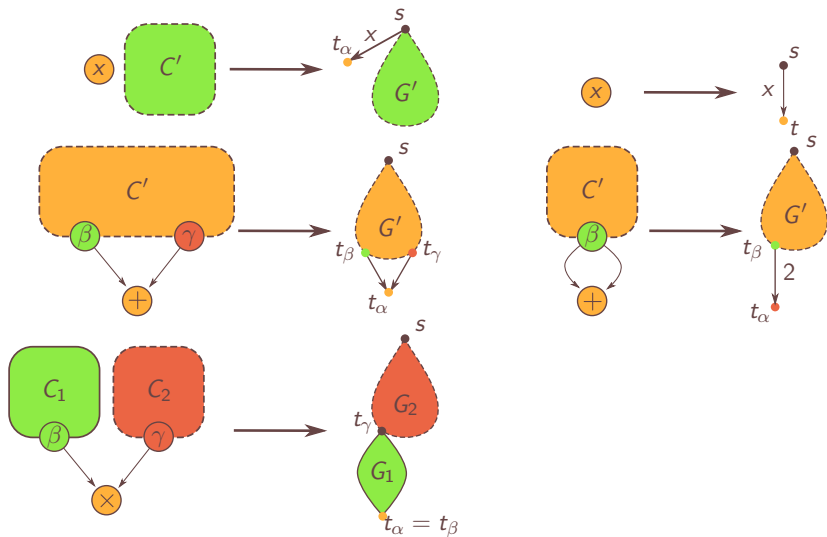
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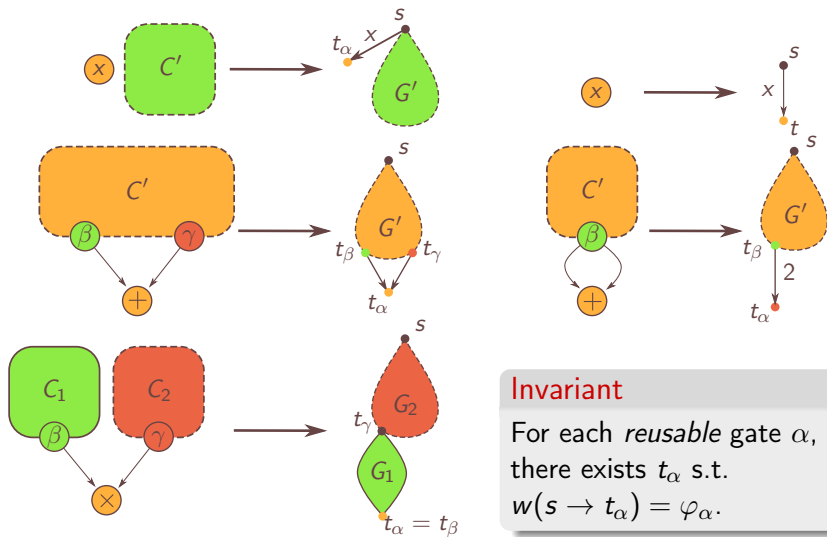
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**Invariant**

For each reusable gate α ,
there exists t_α s.t.
 $w(s \rightarrow t_\alpha) = \varphi_\alpha$.

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Theorem

For a ws circuit of size e with i variable inputs representing φ , this construction yields a size- $(e + i + 1)$. The determinant of its adjacency matrix equals φ .

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- 1 From polynomials to determinants
- 2 From polynomials to determinants of symmetric matrices**
- 3 Characteristic 2
- 4 Comparison with Convex Geometry Literature

Motivation from Convex Geometry

- Linear Matrix Expression (LME): for A_i symmetric in $\mathbb{R}^{t \times t}$

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- What about **polynomial size matrices**?

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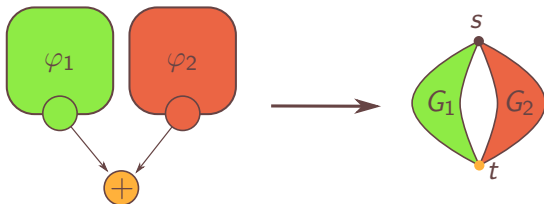
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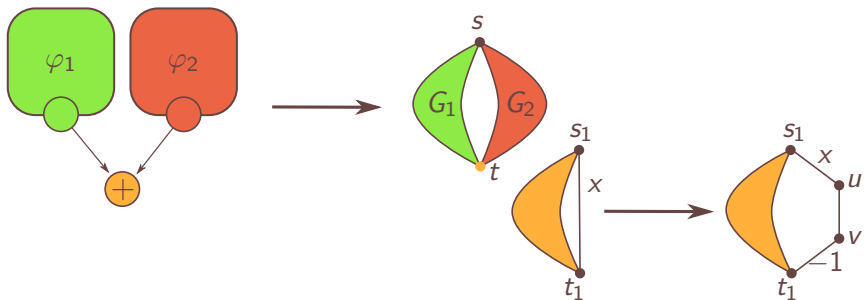
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- N.B.: $\text{char}(\mathbb{K}) \neq 2$ in this section

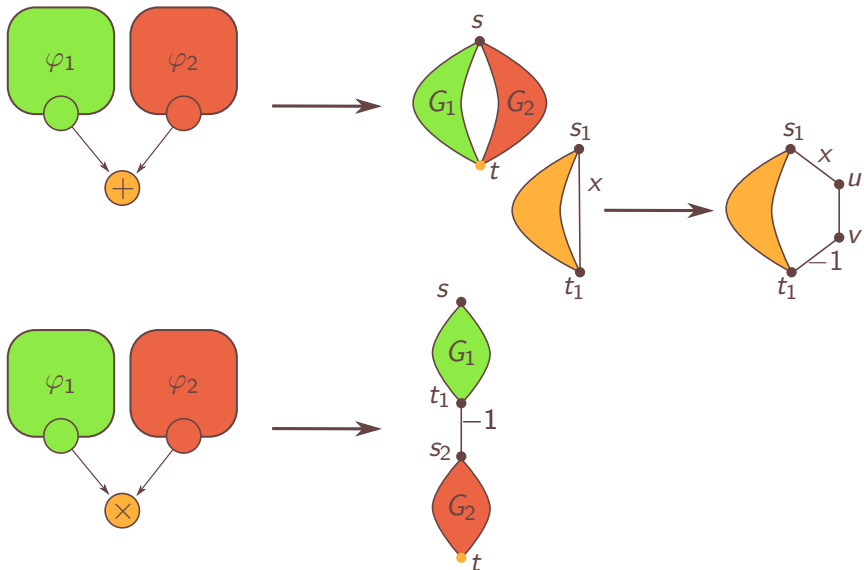
Algorithm



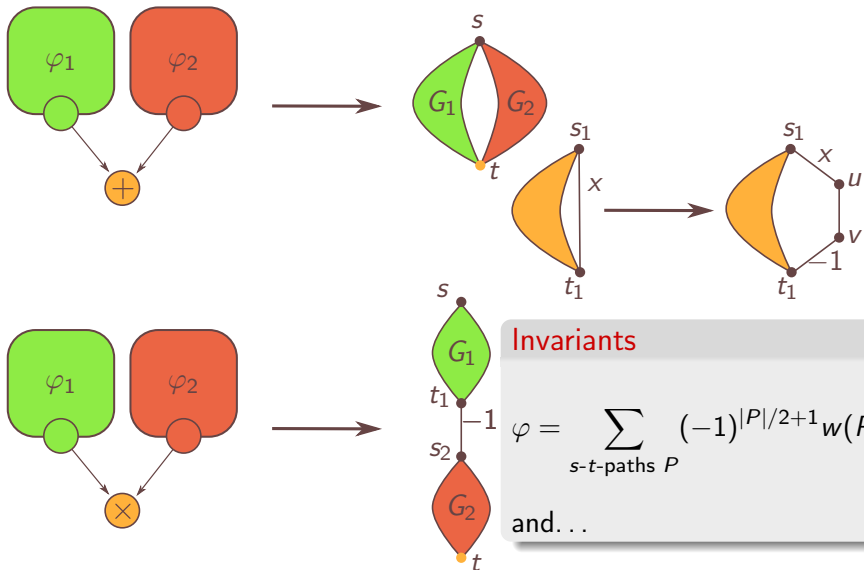
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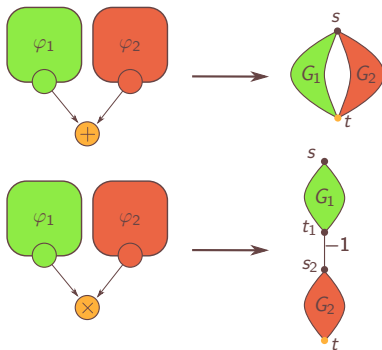
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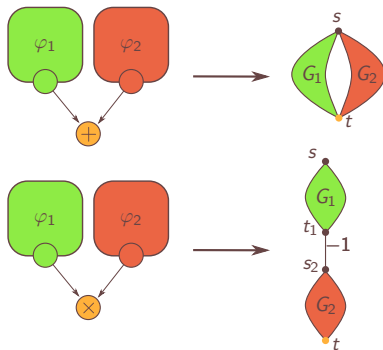
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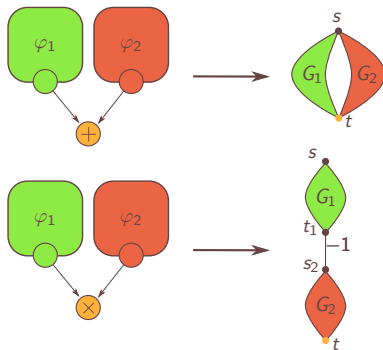
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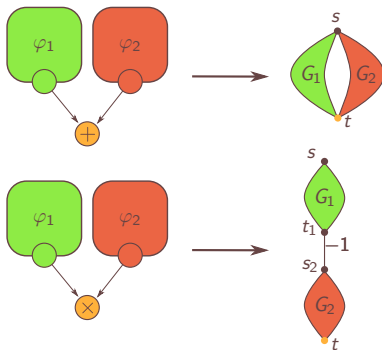
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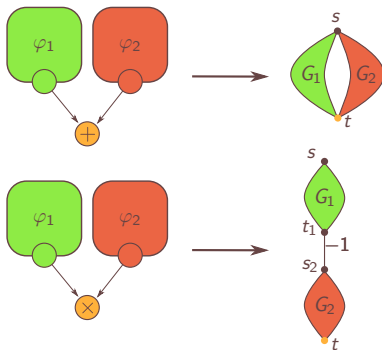
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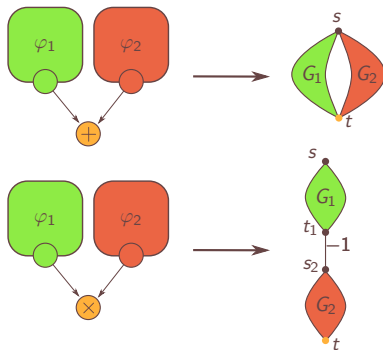
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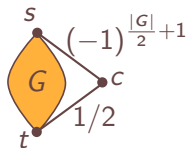
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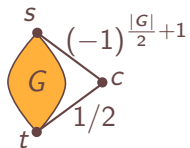


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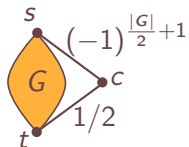
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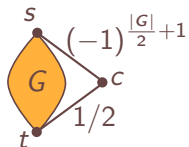
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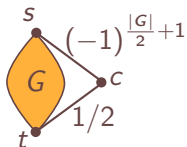
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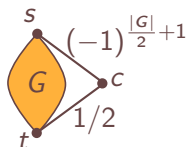
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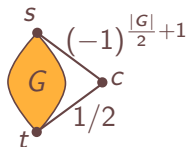
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Theorem

For a formula φ of size e , this construction yields a graph of size $2e + 3$. The determinant of its adjacency matrix equals φ .

Introduction

- Main difficulty:



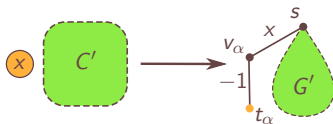
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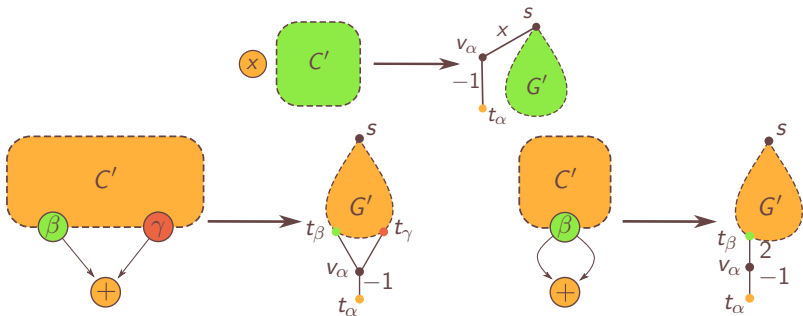


- Definition: an path P is said **acceptable** if $G \setminus P$ admits a cycle cover

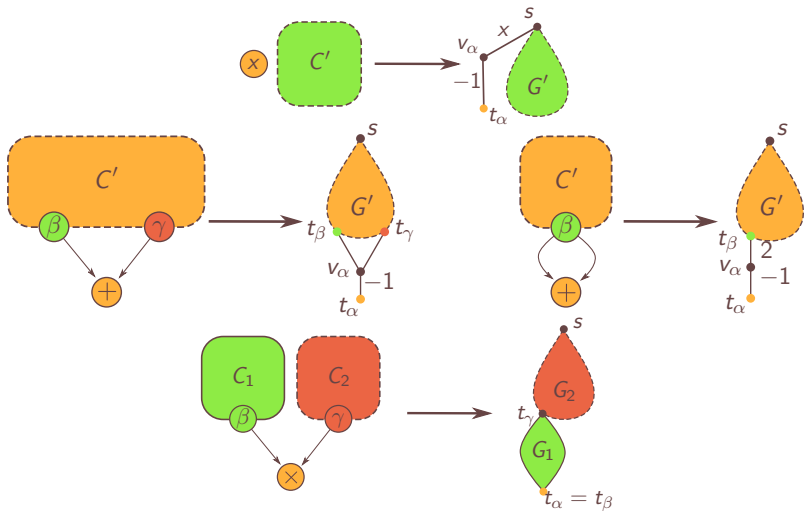
Constructions



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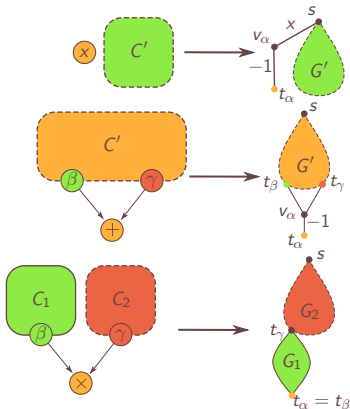


Constructions



Invariants in the case of weakly-skew circuits

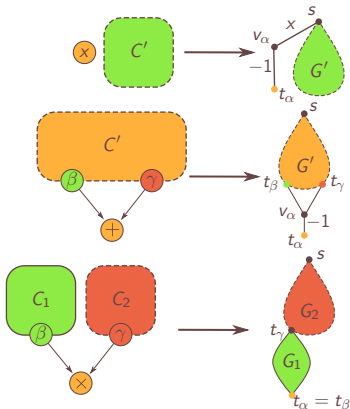
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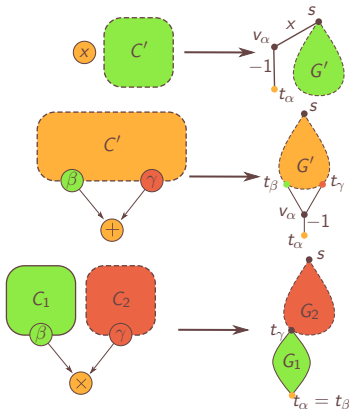
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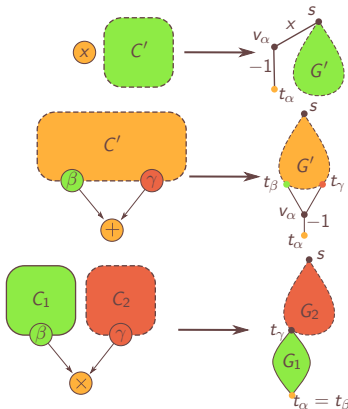


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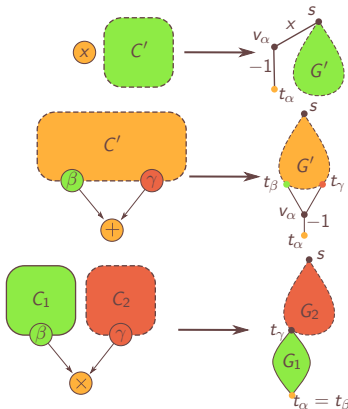


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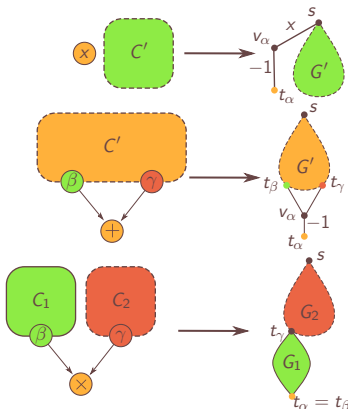
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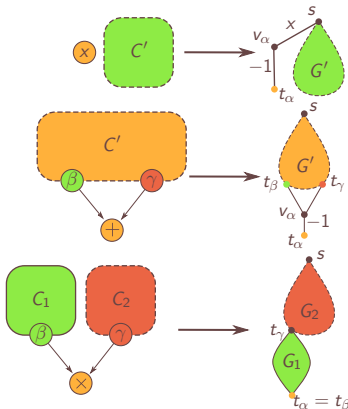
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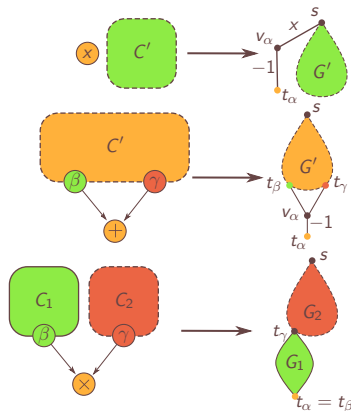
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For a weakly skew circuit of size e , with i input variables, computing a polynomial φ , this construction yields a graph G' with $2(e + i) + 1$ vertices. The adjacency matrix of G' has its determinant equal to φ .

Outline

- 1 From polynomials to determinants
- 2 From polynomials to determinants of symmetric matrices
- 3 Characteristic 2**
- 4 Comparison with Convex Geometry Literature

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A positive result

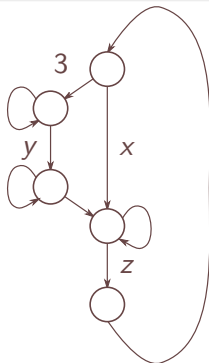
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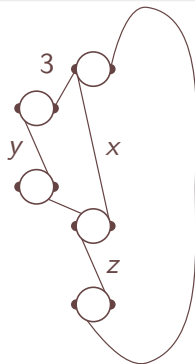


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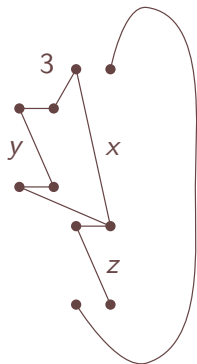


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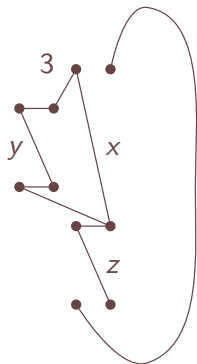


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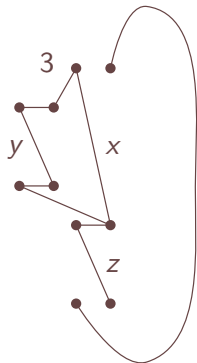


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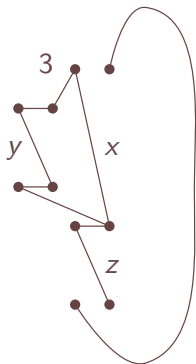


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Outline

- 1 From polynomials to determinants
- 2 From polynomials to determinants of symmetric matrices
- 3 Characteristic 2
- 4 Comparison with Convex Geometry Literature**

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Let p a degree- d polynomial in n variables. Then p admits a formula of size

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Thank you!