

Introducing Physical Relaxation Terms in Bloch Equations¹

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The Bloch equation models the evolution of the state of electrons in matter described by a Hamiltonian. To model more physical phenomena we have to introduce phenomenological relaxation terms. The introduction of these terms has to conserve some positiveness properties. The aim of this paper is to review possible relaxation models and to provide insight into how to discretize them properly in view of numerical computations. © 2001 Academic Press

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1. INTRODUCTION

Today, laser sources make it possible to produce light pulses that are increasingly powerful and shorter. The propagation of such beams through a medium induces nonlinear lightmatter interactions. Moreover, as the pulse duration is of the same order as or even much smaller than the time response of the medium, transient phenomena have to be considered. Thus models are formed in the time domain.

The classical description of the propagation of an electromagnetic wave is given by the Maxwell equations, where the influence of the matter is expressed through polarization. A simple description involving the refractive index is not sufficient, even when it is frequency and intensity dependent. Here, very precise modeling is required for matter. This is performed by Bloch equations, which are derived in the context of quantum mechanics. These equations deal with the probabilistic description of the population of each energy level of the atoms that constitute the matter and the coherence between these levels. These variables are gathered in a so-called density matrix. Statistical averaging over atoms is taken into account by the introduction of relaxation terms. These terms are also necessary to model some important physical phenomena, such as spontaneous emission and collisions. There

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are different classical ways to introduce them [3, 4, 6], but we present here the most general model, i.e., "Pauli's master equation" model.

The relaxation terms that we introduce should preserve some important properties that would be valid without these additional terms. First, populations should be positive and less than 1. Coherences should not be greater than the related populations and density matrices should be positive matrices. In the absence of statistical averaging (and therefore relaxation) all these properties are straightforward, as is emphasized below.

We do not know of any existing literature on this specific problem of conservation of positiveness properties while relaxation terms are added. The reasons may be the following. As we show, positiveness is conserved in all classical physical contexts; hence this is not a problem for physicists. From the numerical point of view, Bloch codes up to now involved only two-level atoms [5, 8, 10] but problems occur with at least three levels. Such a study is useful for our multilevel code and the simulation of physical contexts that involve more than two levels and different relaxation terms, such as a laser cavity. The scope of this paper is limited to the Bloch equations with a given electromagnetic field; the problem of the coupling with a propagation model is postponed for further study.

In Section 2 we give a brief description of the Bloch equations. Section 3 is devoted to the introduction of Pauli's master equation model. A time semidiscretization of the Bloch equation is dealt with in Section 4. This discretization conserves positiveness and is tractable for real numerical computations.

2. BLOCH EQUATIONS

In quantum mechanics, matter is defined by state vectors $|\psi\rangle$, the time evolution of which is given by the Schrödinger equation

$$i\hbar\partial_t|\psi\rangle=H|\psi\rangle.$$

The Hamiltonian H is composed of the unperturbed Hamiltonian H_0 and the perturbation V induced by the electromagnetic field: $H = H_0 + V$. Following a standard approach we decompose $|\psi\rangle$ on the basis of eigenstates of the unperturbed Hamiltonian H_0 . These quantum states $|j\rangle$ are the eigenfunctions of H_0 that correspond to the j th level of energy $\mathcal{E}_j = \hbar \omega_j$ of unperturbed atoms. The set of all these (suitably normalized) quantum states forms a basis of all quantum states. We therefore may set $|\psi\rangle = \sum a_j |j\rangle$ and define the (infinite dimensional) density matrix ρ as $\rho_{jk} = \sum_S a_j^S a_k^{*S}$, where S is a statistical set. This is a solution to

$$i\hbar\partial_t \rho = [H, \rho],\tag{1}$$

where $[\cdot, \cdot]$ denotes the commutator of two operators. Keeping only N relevant levels, ρ is an $N \times N$ Hermitian nonnegative matrix. Its diagonal elements ρ_{jj} represent the population of levels $|j\rangle$ and its off-diagonal elements ρ_{jk} the coherences between levels $|j\rangle$ and $|k\rangle$.

To express the perturbation V, we restrict ourselves to dipole moments because they induce the larger order in the perturbation series. Perturbation V reads $V = -e\vec{E} \cdot \vec{R}$, taking into account that \vec{E} does not significantly vary over atomic distances. The dipole moment matrix is defined by its elements $\vec{p}_{jk} = \langle k|e\vec{R}|j \rangle$. With these notations Eq. (1) yields

$$\partial_t \rho_{jk} = -i\omega_{jk}\rho_{jk} + \frac{i}{\hbar}\vec{E} \cdot [\vec{p}, \rho]_{jk}, \tag{2}$$

where $\omega_{jk} = \omega_j - \omega_k$ is the frequency associated with the transition from level $|k\rangle$ to level $|j\rangle$.

In the expression for V, \vec{E} may be a given field or may be the solution of the Maxwell equations. In the latter case there is a coupling between the Bloch equations and the Maxwell equations via the constitutive relation $\vec{D} = \varepsilon_0 \vec{E} + \vec{P}$, where the polarization \vec{P} is given in terms of the density matrix by $\vec{P} = N_a \operatorname{Tr}(\vec{p}\rho)$, and N_a is the density of atoms.

3. PAULI'S MASTER EQUATION MODEL

To derive the Bloch equations the following hypothesis is made: the stochastic process driving the statistical distribution S is stationary. This is, however, not the case and it is not possible to obtain any information about this process. Other phenomena are not included in the original model, the main one being spontaneous emission of light, but also collisions, vibrations in crystal lattices, or thermal perturbations in fluids. The only way to take all these phenomena into account is to add phenomenological relaxation terms to Eq. (2), which becomes

$$\partial_t \rho_{jk} = -i\omega_{jk}\rho_{jk} - \frac{i}{\hbar}[V, \rho]_{jk} + Q(\rho)_{jk}. \tag{3}$$

The addition of relaxation terms for a coherence only involves this variable, and therefore for $j \neq k$, $Q(\rho)_{jk} = -\gamma_{jk}\rho_{jk}$. Models for diagonal relaxation terms are of several kinds but may be shown to be submodels of Pauli's master equation model, where

$$Q(\rho)_{jj} = \sum_{l \neq j} W_{jl} \rho_{ll} - \sum_{l \neq j} W_{lj} \rho_{jj} = \sum_{l \neq j} W_{jl} \rho_{ll} - \Gamma_j \rho_{jj}. \tag{4}$$

The relaxation to equilibrium states is obtained by imposing

$$W_{jl} = W_{lj}e^{\beta(\mathcal{E}_j - \mathcal{E}_l)} \tag{5}$$

(see, e.g., Bloembergen [3]). Here, $\beta = 1/\kappa T$, where κ is Boltzmann's constant and T is the temperature.

In what follows we suppose that some physical properties are satisfied for the initial data and try to find conditions for the relaxation operator to propagate them for all time.

3.1. Physical Properties

The most obvious property for ρ is that it is Hermitian (i.e., it is an observable quantity from the quantum mechanical point of view). The only way to ensure this property is for equations for ρ_{jk} and ρ_{kj} to be conjugate. Therefore γ_{jk} and γ_{kj} should be equal, which is indeed the choice that is always made.

All relevant energy levels are assumed to be kept in the model which may be expressed as $\text{Tr}(\rho) = 1$. This property is conserved since (3) yields a priori $\partial_t \text{Tr}(\rho) = \text{Tr}(Q(\rho))$ and the specific relaxation operator Q given by (4) ensures that $\text{Tr}(Q(\rho)) = 0$.

The other properties we want to preserve while adding relaxation terms are positiveness properties. First, populations should be nonnegative. They also should be less than one, but this is a consequence of positiveness and the above trace property. The coherence of

two levels has also to be controlled by the population of both levels, or more precisely, $|\rho_{jk}|^2 \le \rho_{jj}\rho_{kk}$. Finally, the whole matrix has to be nonnegative.

3.2. Positiveness

To study positiveness we note that it is preserved by the relaxation-free model (see Section 4.1) and we use the Trotter–Kato formula, which ensures that

$$\rho(t) = e^{t(L+Q)}\rho(0) = \lim_{n \to \infty} \left(e^{tL/n} e^{tQ/n} \rho(0) \right)^n,$$

where $L\rho_{jk} = -i\omega_{jk}\rho_{jk} - \frac{i}{\hbar}[V,\rho]_{jk}$. Therefore it is sufficient that the equation

$$\partial_t \rho = Q(\rho) \tag{6}$$

preserves positiveness properties. In the rest of this section proofs address this equation. All the proofs assume that the quantities we study are nonnegative at time t = 0.

Positiveness of populations. Given a level k, we consider the initial data $\rho_{jj} = \delta_{jk}$. For $j \neq k$, we have $\partial_t \rho_{jj}(0) = W_{jk}$. Since $\rho_{jj}(0) = 0$, its derivative should not be negative and therefore a necessary condition is $W_{jk} \geq 0$.

This necessary condition is also sufficient: if at time t_0 , $\rho_{jj}(t_0) = 0$, then $\partial_t \rho_{jj}(t_0) = \sum_{k \neq j} W_{kj} \rho_{kk}(t_0)$. Since there exists $k_0 \neq j$ such that $\rho_{k_0k_0}(t_0) \neq 0$ (see the trace property), we show that if $W_{jk_0} > 0$ either $t_0 = 0$, and for t > 0, but small, $\rho_{jj}(t) > 0$, or $t_0 \neq 0$, and it is not possible that $\rho_{jj}(t_0) = 0$. Thus if W is a matrix with positive coefficients, $\rho_{jj}(t)$ is positive for t > 0. Besides, $\rho(t)$ is continuous with respect to the matrix W; hence if W is only nonnegative $\rho_{jj}(t)$ remains nonnegative for all time t > 0. The first condition on matrix W is the following.

Condition 3.1. A necessary and sufficient condition for populations to be nonnegative (and less than 1 via the trace property) is that matrix W have nonnegative coefficients.

We notice that this condition is always verified from a physical point of view.

Estimate for the coherences. We set $f(t) \equiv \rho_{jj}(t)\rho_{kk}(t) - \rho_{jk}(t)\rho_{kj}(t)$ and suppose that $f(t_0)$ is zero for time t_0 , but we are not interested in the case when $\rho_{jj}(t_0)\rho_{kk}(t_0) = 0$, i.e., when $\rho_{jk}(t_0) = 0$, for which $\rho_{jk} \equiv 0$ for all time. We notice that $\rho_{jj}(t)\rho_{kk}(t) \geq 0$ is the consequence of Condition 3.1. Computing f' we obtain for a general time t

$$f'(t) = 2\gamma_{jk} f(t) + (2\gamma_{jk} - \Gamma_j - \Gamma_k + \sqrt{W_{jk} W_{kj}}) \rho_{jj}(t) \rho_{kk}(t) + (W_{jk} \rho_{kk} - W_{kj} \rho_{jj})^2$$

$$+ \rho_{jj}(t) \sum_{l \neq j,k} W_{kl} \rho_{ll}(t) + \rho_{kk}(t) \sum_{l \neq j,k} W_{jl} \rho_{ll}(t).$$

If $2\gamma_{jk} - \Gamma_j - \Gamma_k + \sqrt{W_{jk}W_{kj}} > 0$, we show (in the same way as above) that f(t) is positive for all positive time. A continuity argument gives the following condition.

Condition 3.2. A necessary and sufficient condition to have the estimate

$$|\rho_{jk}(t)| \le \sqrt{\rho_{jj}(t)\rho_{kk}(t)}$$

for all time $t \ge 0$ is that $2\gamma_{jk} \ge \Gamma_j + \Gamma_k - \sqrt{W_{jk}W_{kj}}$.

The fact that the condition is necessary is proved by assuming that $\rho_{ll} = 0$ for $l \neq j, k$. Condition 3.2 is also a physical condition (see, e.g., [7]). Off-diagonal decay rates have

the same source as diagonal decay rates plus some extra sources, such as elastic collision broadening. Therefore, γ_{jk} is often written as $\gamma_{jk} = \frac{1}{2}(\Gamma_j + \Gamma_k) + \gamma_{jk}^{coll}$, where $\gamma_{jk}^{coll} \geq 0$. In many physical contexts we even have $\gamma_{jk}^{coll} \gg \Gamma_j + \Gamma_k$. Moreover, γ_{jk}^{coll} very often does not depend on j and k.

In what follows we are unable to treat a condition including the expression $\sqrt{W_{jk}W_{kj}}$, but we give a specific form for γ_{jk} that covers all physical models,

$$\gamma_{jk} = \frac{1}{2}(\Gamma_j + \Gamma_k) + \gamma_j^{coll} + \gamma_k^{coll} - A_j \cdot A_k, \tag{7}$$

where $\gamma_i^{coll} \in \mathbb{R}$ and $A_i \in \mathbb{R}^N$.

Positiveness of the density matrix. Let $X=(x_1,\ldots,x_N)\in\mathbb{C}^N$ and $g(t)=X^*\rho(t)X$. We assume that t_0 is the first time for which $g(t_0)=0$. At time $t_0,\,\rho(t_0)$ is a Hermitian nonnegative matrix and we may state that $\rho(t_0)X=0$ and $X^*\rho(t_0)=0$. Then

$$\begin{split} g'(t) &= \sum_{j} \sum_{k \neq j} W_{jk} \rho_{kk} |x_{j}|^{2} - \sum_{j} \Gamma_{j} \rho_{jj} |x_{j}|^{2} - \sum_{j,k,j \neq k} \gamma_{jk} x_{j}^{*} \rho_{jk} x_{k} \\ &= \sum_{j} \sum_{k \neq j} W_{jk} \rho_{kk} |x_{j}|^{2} + \sum_{j} \left(2 \gamma_{j}^{coll} - \|A_{j}\|^{2} \right) \rho_{jj} |x_{j}|^{2} \\ &- \sum_{j} \left(\frac{1}{2} \Gamma_{j} + \gamma_{j}^{coll} \right) x_{j}^{*} \underbrace{\left(\sum_{k} \rho_{jk} x_{k} \right)}_{=0} - \sum_{k} \left(\frac{1}{2} \Gamma_{k} + \gamma_{k}^{coll} \right) \underbrace{\left(\sum_{j} x_{j}^{*} \rho_{jk} \right)}_{=0} x_{k} \\ &+ \sum_{k} \underbrace{\sum_{j} \sum_{k} \gamma_{k} (a_{j}^{l} x_{j})^{*} \rho_{jk} (a_{k}^{l} x_{k})}_{\geq 0} \\ &= \sum_{j} \sum_{k \neq j} W_{jk} \rho_{kk} |x_{j}|^{2} + \sum_{j} \left(2 \gamma_{j}^{coll} - \|A_{j}\|^{2} \right) \rho_{jj} |x_{j}|^{2} \\ &+ \sum_{l} \underbrace{\sum_{j} \sum_{k} \gamma_{k} (a_{j}^{l} x_{j})^{*} \rho_{jk} (a_{k}^{l} x_{k})}_{>0} . \end{split}$$

A sufficient condition for g(t) to be positive is therefore $\gamma_j^{coll} > \frac{1}{2} \|A_j\|^2$ for all j and it is relaxed by continuity to the condition for g(t) to be nonnegative, $\gamma_i^{coll} \ge \frac{1}{2} \|A_j\|^2$.

Condition 3.3. With the hypothesis (7) on collisional decay rates, a sufficient condition for ρ to be a nonnegative matrix for all time is $\gamma_i^{coll} \ge \frac{1}{2} \|A_j\|^2$ for all j.

We note that Condition 3.3 is more general than Condition 3.2. Besides, the most widely used physical model corresponds to $A_j \equiv 0$ and $\gamma_j^{coll} = \frac{1}{2}\gamma^{coll}$; i.e., $\gamma_{jk} = \frac{1}{2}(\Gamma_j + \Gamma_k) + \gamma^{coll}$.

Remark. Condition (7) may be written as $2\gamma_{jk} = \Gamma_j + \Gamma_k + ||B_j - B_k||$ for $B_j \in \mathbb{C}^N$.

4. NUMERICAL ISSUES

The most commonly used time discretization for the Bloch equations is the Crank-Nicolson scheme. For example, Ziolkowski *et al.* [10], who have studied the Maxwell-Bloch equation, use this scheme coupled to a Yee scheme for the Maxwell equation. Nagra

and York [9], while studying a coupling between the Maxwell equations and the rate equation (involving only populations), also use this centered scheme. We show that this approach is indeed valid for two-level Bloch equations. But for a greater number of energy levels positiveness is no longer preserved; for example, negative populations may actually be observed numerically.

Some other methods are also present in the literature. Martín *et al.* [8] use a multigrid approach with a leap-frog scheme in the case of two-level atoms and in the slowly varying envelope approximation for the electromagnetic field. There are at least two ways to write their scheme in our context, since for two-level equations the coherences do not appear in the expression of the interaction terms in the evolution equation for the coherences. This scheme is also not positiveness preserving.

We give an alternative discretization for the Bloch equation that does apply in a general framework. We do not comment on how the Bloch equations may be coupled to a model for the propagation of the electromagnetic field. Indeed, this problem, which is important for full Maxwell–Bloch simulations, is not directly connected to the introduction of relaxation terms and to the conservation of positiveness properties. We refer to [1] for a discussion on the time coupling of Maxwell and Bloch equations.

4.1. Analysis of the Crank-Nicolson Scheme

The problem with the Crank–Nicolson scheme is not connected to the relaxation operator; therefore we explain it for the relaxation-free model (1). Given a time step δt , the Crank–Nicolson scheme reads

$$\frac{\rho^{n+1} - \rho^n}{\delta t} = -\frac{i}{\hbar} \left(H^{n+1/2} \frac{\rho^{n+1} + \rho^n}{2} - \frac{\rho^{n+1} + \rho^n}{2} H^{n+1/2} \right),$$

where ρ^n and $H^{n+1/2}$ are, respectively, approximations of $\rho(n\delta t)$ and $H(n\delta t + \frac{\delta t}{2})$. We choose approximations such that $H^{n+1/2}$ is Hermitian, and therefore we may diagonalize it in some basis, yielding $\tilde{H}^{n+1/2} = \operatorname{diag}(\lambda_1^{n+1/2}, \dots, \lambda_N^{n+1/2})$. Writing ρ^n in this basis gives $\tilde{\rho}^n$, which is a solution to

$$\frac{\tilde{\rho}_{jk}^{n+1} - \tilde{\rho}_{jk}^{n}}{\delta t} = -\frac{i}{\hbar} \left(\lambda_{j}^{n+1/2} \frac{\rho_{jk}^{n+1} + \rho_{jk}^{n}}{2} - \lambda_{k}^{n+1/2} \frac{\rho_{jk}^{n+1} + \rho_{jk}^{n}}{2} \right)$$

or explicitly

$$\tilde{\rho}_{jk}^{n+1} = \frac{1 - \frac{i\delta t}{2\hbar} (\lambda_j^{n+1/2} - \lambda_k^{n+1/2})}{1 + \frac{i\delta t}{2\hbar} (\lambda_j^{n+1/2} - \lambda_k^{n+1/2})} \tilde{\rho}_{jk}^{n}.$$

This does not lead to a positive matrix $\tilde{\rho}^{n+1}$, provided $\tilde{\rho}^n$ is positive. To understand this point we have to compare with the continuous case. We may diagonalize the system (1) for all time t and obtain

$$i\hbar\tilde{\rho}'_{ik}(t) = (\lambda_j(t) - \lambda_k(t))\tilde{\rho}_{jk}(t)$$

and for all $X = (x_1, \ldots, x_N) \in \mathbb{C}^N$, $\sum_{jk} x_j^* \tilde{\rho}_{jk}(t) x_k = \sum_{jk} y_j^* \tilde{\rho}_{jk}(0) y_k$, where $y_j = x_j$ exp $(-\frac{i}{\hbar} \int_0^t \lambda_j(s) \, ds)$. The discrete multiplicator is an approximation of $\exp(-\frac{i}{\hbar} \int_0^t (\lambda_j(s) - \lambda_k(s)) \, ds)$ but does not have the property of splitting into a j and a k contribution. In [10],

Ziolkowski *et al.* only treat two-level atoms and this problem does not occur since there is only one off-diagonal term.

4.2. An Alternative Method

The alternative method we introduce is based on a splitting procedure; i.e., we solve separately

$$\partial_t \rho = L \rho, \tag{8}$$

where $(L\rho)_{jk} = -i\omega_{jk}\rho_{jk} + Q(\rho)_{jk}$, and

$$i\hbar\partial_t \rho = [V, \rho]. \tag{9}$$

In Eq. (8) the linear operator is constant and $\rho(t+\delta t)=\exp(L\delta t)\rho(t)$. Therefore we may compute $\exp(L\delta t)$ once and for all and apply it at each time step. Equation (9) is solved exactly by $\rho(t+\delta t)=\exp(\frac{iV}{\hbar}\delta t)\rho(t)\exp(-\frac{iV}{\hbar}\delta t)$, but it would be too expensive to implement the diagonalization that is used for the proof mentioned above at each time step since V depends a priori on time (and space if the system is coupled to a model of the field). We replace the exact solution by the approximate solution $\rho(t+\delta t)\sim (I-\frac{i\delta t}{2\hbar}V)^{-1}(I+\frac{i\delta t}{2\hbar}V)\rho(t)(I-\frac{i\delta t}{2\hbar}V)(I+\frac{i\delta t}{2\hbar}V)^{-1}$, where V is linear with respect to E and the inverse matrices may be computed via the Fadeev formula. This leads to a very efficient implementation of the scheme. The advantage of this splitting is that it preserves positiveness for each of these equations. Indeed, both steps (8) and (9) preserve positiveness. The numerical solution of the first step is exact, since we compute the matrix $\exp(L\delta t)$, and the approximation of the second step preserves positiveness, $X^*\rho(t+\delta t)X=Y^*\rho(t)Y$ with $Y=(I-\frac{i\delta t}{2\hbar}V)(I+\frac{i\delta t}{2\hbar}V)^{-1}X$. Last, with these two steps it is possible to design methods with any order of accuracy, although it is not worthwhile to do so if the model for the electromagnetic field that might be coupled with it has a low order of accuracy.

If we write, for example, the second-order scheme, we have

$$\rho^{n+1} = e^{L\delta t/2} \left(I - \frac{i\delta t}{2\hbar} V \right)^{-1} \left(I + \frac{i\delta t}{2\hbar} V \right) e^{L\delta t/2} \rho^n(t) \left(I - \frac{i\delta t}{2\hbar} V \right) \left(I + \frac{i\delta t}{2\hbar} V \right)^{-1}.$$

The Appendix shows that $M_N=(I-\frac{i\delta t}{2\hbar}V)(I+\frac{i\delta t}{2\hbar}V)^{-1}$ reads $I+\delta t\phi(V,\delta t)$, where $\phi(V,\delta t)$ is bounded for $\delta t\leq \delta t_0$ for any δt_0 . The operator $e^{L\delta t/2}$ also reads $I+\delta t\psi(\delta t)$, where $\psi(\delta t)$ is bounded for $\delta t\leq \delta t_0$. Let us gather all the real variables (the diagonal elements and the real and imaginary parts of the off-diagonal elements) of the density matrix ρ^n in a vector y^n . Therefore, we may write the splitting scheme as $y^{n+1}=y^n+\delta t\Phi(t_n,y^n,\delta t)$, where for all δt_0 , $\Phi(t_n,y^n,\delta t)$ is Lipschitz in the second variable uniformly with respect to $\delta t\leq \delta t_0$. The dependence in $t_n=n\delta t$ comes from V, which is assumed to be Lipschitz in time as well (it is a sine function in our test cases). This is a sufficient condition for stability.

4.3. Some Applications

We present here some computations of the Bloch equations with a given electric field. We focus on performance and the illustration of the use of different relaxation terms. Coupling with a Maxwell solver leads to richer physical phenomena and we refer to [2] for examples in a one-dimensional space. Research in higher dimensions is in progress.

Comparison of different numerical schemes. In this section we compare three schemes. The first one is the Crank–Nicolson scheme which is also the scheme that is the most widely used. We also tried a relaxation scheme where diagonal terms (ρ_d) are computed at times $n\delta t$ and off-diagonal terms (ρ_{od}) at time $(n+\frac{1}{2})\delta t$, namely

$$\begin{split} \frac{\rho_{od}^{n+1/2} - \rho_{od}^{n-1/2}}{\delta t} &= Rn \left(\frac{\rho_{od}^{n+1/2} + \rho_{od}^{n-1/2}}{2} \right) - \frac{i}{\hbar} \bigg[V^n, \frac{\rho_{od}^{n+1/2} + \rho_{od}^{n-1/2}}{2} + \rho_d^n \bigg], \\ \frac{\rho_d^{n+1} - \rho_d^n}{\delta t} &= Rn \left(\frac{\rho_d^{n+1} + \rho_d^n}{2} \right) - \frac{i}{\hbar} \big[V^{n+1/2}, \rho_{od}^{n+1/2} \big]. \end{split}$$

Such a scheme is of no interest in the case of a forced electromagnetic field but leads to less coupled equations in the case of Maxwell–Bloch equations (see [1]). Last, we tested the splitting scheme that we describe in Section 4.2. In a two-level Bloch code, one diagonal variable is usually not computed and replaced by the trace conservation law. This would lead to unnecessary complications in the implementation of a multilevel code, and therefore we test the different methods with respect to trace conservation, positiveness conservation, and CPU times. To show the differences we have to run a large number of iterations. Figure 1 shows iterations 24,000 to 25,000 for a given relaxation-free test. The time step is chosen to be lower than 1/(10 f), where $f = \max(|\omega_{12}|, \gamma^{coll})$.

The details of the evolution are not important for our demonstration. Solutions are highly oscillatory because the field is monochromatic and its frequency exactly matches the matter

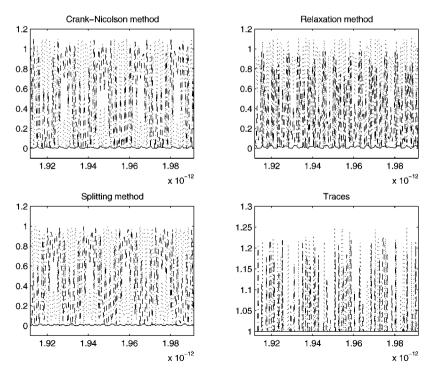


FIG. 1. Comparison of different numerical schemes. The first three plots represent the time evolution of populations for three-level atoms and for different numerical schemes. The last plot represents the time evolution of the trace for the Crank–Nicolson scheme (dash-point), the relaxation scheme (points), and the splitting scheme (solid).

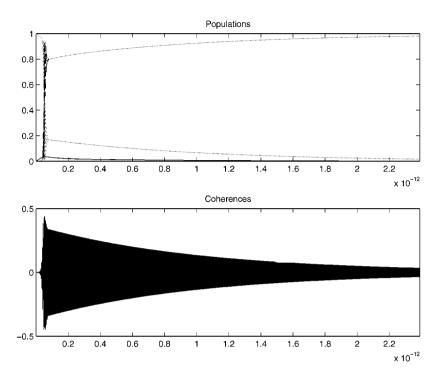


FIG. 2. Different relaxation rates. Relaxation rates are $W_{21} = 10^{12}$ and $W_{32} = 10^{13}$.

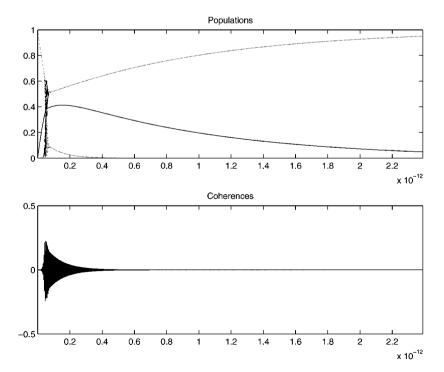


FIG. 3. Different relaxation rates. Relaxation rates are $W_{21} = 10^{13}$ and $W_{32} = 10^{12}$.

transitions. The important point is the range of the values for the populations. We see that the Crank–Nicolson method and the relaxation method do not preserve positiveness (i.e., populations do not lie in the interval [0, 1]), as well as the trace property, while the splitting method does. Estimates of coherences are not presented here but are wrong also. Besides, CPU times are 23 s for the Crank–Nicolson scheme, 27 s for the relaxation scheme (and indeed no improvement was expected with a given field), and 11 s for the splitting scheme. Finally, the dynamics seems to be the same (up to a small shift) for the Crank–Nicolson method and the splitting method but qualitatively different for the relaxation scheme. For all these reasons the splitting method is used for further tests.

Simulations with different relaxation rates. This section demonstrates that being able to handle different relaxation rates helps to describe the wide variety of transient behavior of systems. In Figs. 2 and 3 are represented the transient and long-time evolution of a medium (where initially $\rho_{11}=1$) under the influence of a wave packet with leading frequency $5\omega_{31}$. Dipole matrix elements are $p_{12}=0$, $p_{13}=10^{-28}$, and $p_{23}=10^{-29}$. In both simulations $W_{13}=0$ and $\gamma^{coll}=0$.

The long-time behavior is also slightly affected by the change of the matrix W according to Eq. (5).

5. CONCLUSION

The introduction of more than two levels into a Bloch model induces some new modeling problems. Multilevel codes are necessary, however, to model physical phenomena, such as coherence transfer [2] and Raman effects. Numerical models that were used until now for two-level atoms are not able to preserve the natural properties of atoms of three or more levels, the main one (or the more visible) of which is that populations may not lie between 0 and 1. We found an alternative method that not only has the advantage of preserving positiveness properties but also allows some gain in computational time. In the case of a coupling with Maxwell equations, it also makes it possible to decouple the computation of the field and the density matrix, thus leading not only to substantial gains in computational time, but also to the efficient parallelization of the code, which could be useful for one-dimensional codes and even more for two- or three-dimensional codes.

APPENDIX

Fadeev Formulas for Two-, Three-, and Four-Level Atoms

We use the Fadeev formula to compute the matrix $M_N = (I - \frac{i\delta t}{2\hbar}V)(I + \frac{i\delta t}{2\hbar}V)^{-1}$ for N-level atoms. This formula gives an algorithm to compute matrix inverses. Indeed, given a matrix A, $A^{-1} = \frac{1}{p_N}B_{N-1}$, where

$$A_1 = A,$$
 $p_1 = \text{Tr } A_1,$ $B_1 = A_1 - p_1 I,$ $A_2 = A B_1,$ $p_2 = \frac{1}{2} \text{Tr } A_2,$ $B_2 = A_2 - p_2 I,$ \vdots \vdots \vdots $A_N = A B_{N-1},$ $p_N = \frac{1}{N} \text{Tr } A_N,$ $B_N = A_N - p_N I = 0.$

In our case $A=I+\varepsilon p$ and $\varepsilon=-\frac{i\delta t}{2\hbar}E$ (in the case of multidimensional spaces, contributions in each direction should be added). Some simplifications are due to the fact that Tr

p = 0. Computations lead to

$$\begin{split} M_2 &= I + \frac{\varepsilon^2 \mathrm{Tr} \ p^2 I - 2\varepsilon p}{1 - \frac{1}{2}\varepsilon^2 \mathrm{Tr} \ p^2}, \\ M_3 &= I + \frac{-\frac{2}{3}\varepsilon^3 \mathrm{Tr} \ p^3 I - 2\varepsilon p + 2\varepsilon^2 p^2}{1 - \frac{1}{2}\varepsilon^2 \mathrm{Tr} \ p^2 + \frac{1}{3}\varepsilon^3 \mathrm{Tr} \ p^3}, \\ M_4 &= I + \frac{\left(-\frac{2}{3}\varepsilon^3 \mathrm{Tr} \ p^3 - \frac{1}{4}\varepsilon^4 (\mathrm{Tr} \ p^2)^2 + \frac{1}{2}\varepsilon^4 \mathrm{Tr} \ p^4\right) I}{1 - \frac{1}{2}\varepsilon^2 \mathrm{Tr} \ p^2 + \frac{1}{3}\varepsilon^3 \mathrm{Tr} \ p^3 + \frac{1}{8}\varepsilon^4 (\mathrm{Tr} \ p^2)^2 - \frac{1}{4}\varepsilon^4 \mathrm{Tr} \ p^4} \\ &- \frac{(2 - \varepsilon^2 \mathrm{Tr} \ p^2)\varepsilon p + 2\varepsilon^2 p^2 - 2\varepsilon^3 p^3}{1 - \frac{1}{2}\varepsilon^2 \mathrm{Tr} \ p^2 + \frac{1}{3}\varepsilon^3 \mathrm{Tr} \ p^3 + \frac{1}{8}\varepsilon^4 (\mathrm{Tr} \ p^2)^2 - \frac{1}{4}\varepsilon^4 \mathrm{Tr} \ p^4}. \end{split}$$

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